

Locomotion

Locomotion

Finalist for the National Book Award When Lonnie was seven years old, his parents died in a fire. Now he's eleven, and he still misses them terribly. And he misses his little sister, Lili, who was put into a different foster home because \"not a lot of people want boys-not foster boys that ain't babies.\" But Lonnie hasn't given up. His foster mother, Miss Edna, is growing on him. She's already raised two sons and she seems to know what makes them tick. And his teacher, Ms. Marcus, is showing him ways to put his jumbled feelings on paper. Told entirely through Lonnie's poetry, we see his heartbreak over his lost family, his thoughtful perspective on the world around him, and most of all his love for Lili and his determination to one day put at least half of their family back together. Jacqueline Woodson's poignant story of love, loss, and hope is lyrically written and enormously accessible.

Peace, Locomotion

The stunning companion to the National Book Award finalist--from a four-time Newbery Honor winning author Twelve-year-old Lonnie is finally feeling at home with his foster family. But because he's living apart from his little sister, Lili, he decides it's his job to be the "rememberer"—and write down everything that happens while they're growing up. Lonnie's musings are bittersweet; he's happy that he and Lili have new families, but though his new family brings him joy, it also brings new worries. With a foster brother in the army, concepts like Peace have new meaning for Lonnie. Told through letters from Lonnie to Lili, this thought-provoking companion to Jacqueline Woodson's National Book Award finalist *Locomotion* tackles important issues in captivating, lyrical language. Lonnie's reflections on family, loss, love and peace will strike a note with readers of all ages.

Animal Locomotion

This book provides a clear foundation, based on physical biology and biomechanics, for understanding the underlying mechanisms by which animals have evolved to move in their physical environment. It integrates the biomechanics of animal movement with the physiology of animal energetics and the neural control of locomotion. The author also communicates a sense of the awe and fascination that comes from watching the grace, speed, and power of animals in motion. Movement is a fundamental distinguishing feature of animal life, and a variety of extremely effective mechanical and physiological designs have evolved. Common themes are observed for the ways in which animals successfully contend with the properties of a given physical environment across diversity of life forms and varying locomotor modes. Understanding the common principles of design that span a diverse array of animals requires a broad comparative and integrative approach to their study. This theme persists throughout the book, as various modes and mechanisms of animal locomotion are covered. Since an animal's size is equally critical to its functional design, the effects of scale on locomotor energetics and mechanics are also discussed. Biewener begins by examining the underlying machinery for movement: skeletal muscles used for force generation, skeletons used for force transmission, and spring-like elements used for energy savings. He then describes the basic mechanisms that animals have evolved to move over land, in and on the surface of the water, and in the air. Common fluid dynamic principles are discussed as background to both swimming and flight. In addition to discussing the locomotor mechanisms of complex animals, the locomotor movement of single cells is also covered. Common biochemical features of cellular metabolism are then reviewed before discussing the energetic aspects of various locomotor modes. Strategies for conserving energy and moving economically are again highlighted in this section of the book. Emphasis is placed on comparisons of energetic features across

locomotor modes. The book concludes with a discussion of the neural control of animal locomotion. The basic neurosensory and motor elements common to vertebrates and arthropods are discussed, and features of sensori-motor organization and function are highlighted. These are then examined in the context of specific examples of how animals control the rhythmic patterns of limb and body movement that underlie locomotor function and stability.

Human Locomotion

Forlagets beskrivelse: In the course of a year, more than 1.9 million runners will fracture at least one bone and approximately 50% will suffer some form of overuse injury that prevents them from running. Despite the widespread prevalence of gait-related injuries, the majority of health care practitioners continue to rely on outdated and ineffective treatment protocols emphasizing passive interventions, such as anti-inflammatory medications and rest. With more than 1000 references and 530 illustrations, Dr. Michaud's text on human locomotion presents a logical approach to the examination, assessment, treatment and prevention of gait-related injuries. Beginning with a complete review of the evolution of bipedality, this textbook goes on to describe the functional anatomy of each joint in the lower extremity, pelvis, and spine. This information is then related to normal and abnormal motions during the gait cycle, providing the most comprehensive description of human locomotion ever published. 'Human Locomotion' also discusses a wide range of conservative interventions, including a detailed guide to manual therapies, a complete review of every aspect of orthotic intervention, along with illustrated explanations of hundreds of rehabilitative stretches and exercises. The final chapter summarizes state-of-the-art, proven conservative treatment interventions, providing specific protocols for dozens of common gait-related injuries, including Achilles tendinitis, plantar fasciitis, stress fractures and hamstring strains. Whether you are a chiropractor, physical therapist, podiatrist or podiatrist, this text provides practical information that will change the way you practice.

Quadrupedal Locomotion

Walking machines have advantages over traditional vehicles, and have already accomplished tasks that wheeled or tracked robots cannot handle. Nevertheless, their use in industry and services is currently limited in scope. This book brings together methods and techniques that have been developed to deal with obstacles to wider acceptance of legged robots. Part I provides an historical overview. Part II concentrates on control techniques, as applied to Four-legged robots.

Understanding Mammalian Locomotion

Understanding Mammalian Locomotion will formally introduce the emerging perspective of collision dynamics in mammalian terrestrial locomotion and explain how it influences the interpretation of form and functional capabilities. The objective is to bring the reader interested in the function and mechanics of mammalian terrestrial locomotion to a sophisticated conceptual understanding of the relevant mechanics and the current debate ongoing in the field.

Bioinspired Legged Locomotion

Bioinspired Legged Locomotion: Models, Concepts, Control and Applications explores the universe of legged robots, bringing in perspectives from engineering, biology, motion science, and medicine to provide a comprehensive overview of the field. With comprehensive coverage, each chapter brings outlines, and an abstract, introduction, new developments, and a summary. Beginning with bio-inspired locomotion concepts, the book's editors present a thorough review of current literature that is followed by a more detailed view of bouncing, swinging, and balancing, the three fundamental sub functions of locomotion. This part is closed with a presentation of conceptual models for locomotion. Next, the book explores bio-inspired body design, discussing the concepts of motion control, stability, efficiency, and robustness. The morphology of legged robots follows this discussion, including biped and quadruped designs. Finally, a section on high-level

control and applications discusses neuromuscular models, closing the book with examples of applications and discussions of performance, efficiency, and robustness. At the end, the editors share their perspective on the future directions of each area, presenting state-of-the-art knowledge on the subject using a structured and consistent approach that will help researchers in both academia and industry formulate a better understanding of bioinspired legged robotic locomotion and quickly apply the concepts in research or products.

Locomotion!

How many ways do we move around? Explore five different kinds of Creative Movement in Locomotion! March, Hop, Skip, Gallop, Run.

Principles of Animal Locomotion

How can geckoes walk on the ceiling and basilisk lizards run over water? What are the aerodynamic effects that enable small insects to fly? What are the relative merits of squids' jet-propelled swimming and fishes' tail-powered swimming? Why do horses change gait as they increase speed? What determines our own vertical leap? Recent technical advances have greatly increased researchers' ability to answer these questions with certainty and in detail. This text provides an up-to-date overview of how animals run, walk, jump, crawl, swim, soar, hover, and fly. Excluding only the tiny creatures that use cilia, it covers all animals that power their movements with muscle--from roundworms to whales, clams to elephants, and gnats to albatrosses. The introduction sets out the general rules governing all modes of animal locomotion and considers the performance criteria--such as speed, endurance, and economy--that have shaped their selection. It introduces energetics and optimality as basic principles. The text then tackles each of the major modes by which animals move on land, in water, and through air. It explains the mechanisms involved and the physical and biological forces shaping those mechanisms, paying particular attention to energy costs. Focusing on general principles but extensively discussing a wide variety of individual cases, this is a superb synthesis of current knowledge about animal locomotion. It will be enormously useful to advanced undergraduates, graduate students, and a range of professional biologists, physicists, and engineers.

Muscles, Reflexes, and Locomotion

This is the first book-length treatment of mathematical models of muscle functions. Although physiologists, biophysicists, and bioengineers often mention these models, particularly the important Huxley models, Thomas A. McMahon is the first completely to explain them.

Dog Locomotion and Gait Analysis

This book is an attempt to advance the discussion and improve our understanding about the effects of aging and movement disorders on motor control during walking and postural tasks. Despite these activities are performed daily, there is a high requirement of motor and neural systems in order to perform both tasks efficiently. Both walking and posture require a complex interaction of musculoskeletal and neural systems. However, the mechanisms used to control these tasks, as well as how they are planned and coordinated, are still a question of discussion among health professionals and researchers. In addition, this discussion is more interesting when the effects of aging are included in the context of locomotion and the postural control. The number of older individuals is 841 million in 2015, which is four times higher than the 202 million that lived in 1950. Aging causes many motor, sensorial and neural deficits, which impair locomotion and postural control in the elderly. The severity of this framework is worsened when the aging goes along with a movement disorder, such as Parkinson disease, Chorea, Dystonia, Huntington disease, etc. Therefore, the aim of this book is to highlight the influence of different aspects on planning, controlling and performing locomotion and posture tasks. In attempting to improve current knowledge in this field, invited authors present and discuss how environmental, sensorial, motor, cognitive and individual aspects influence the planning and performance of locomotor and postural activities. The major thrust of the book is to address the

mechanisms involved in controlling and planning motor action in neurological healthy individuals, as well as in those who suffer from movement disorders or face the effects of aging, indicating the aspects that impair locomotion and postural control. In addition, new technologies, tools and interventions designed to manage the effects of aging and movement disorders are presented in the book.

Locomotion and Posture in Older Adults

This highly illustrated and comprehensive new book discusses all aspects of equine locomotion and gait analysis. Written by an international team of editors and contributors, with leading experts from the USA, the Netherlands, Sweden and France (all centres of excellence for the study of equine locomotion).

Equine Locomotion

Bipedal locomotion is among the most difficult challenges in control engineering. Most books treat the subject from a quasi-static perspective, overlooking the hybrid nature of bipedal mechanics. *Feedback Control of Dynamic Bipedal Robot Locomotion* is the first book to present a comprehensive and mathematically sound treatment of feedback design for achieving stable, agile, and efficient locomotion in bipedal robots. In this unique and groundbreaking treatise, expert authors lead you systematically through every step of the process, including: Mathematical modeling of walking and running gaits in planar robots Analysis of periodic orbits in hybrid systems Design and analysis of feedback systems for achieving stable periodic motions Algorithms for synthesizing feedback controllers Detailed simulation examples Experimental implementations on two bipedal test beds The elegance of the authors' approach is evident in the marriage of control theory and mechanics, uniting control-based presentation and mathematical custom with a mechanics-based approach to the problem and computational rendering. Concrete examples and numerous illustrations complement and clarify the mathematical discussion. A supporting Web site offers links to videos of several experiments along with MATLAB® code for several of the models. This one-of-a-kind book builds a solid understanding of the theoretical and practical aspects of truly dynamic locomotion in planar bipedal robots.

Feedback Control of Dynamic Bipedal Robot Locomotion

Written in 1950, this was the first book to thoroughly analyze, illustrate and explain the under-the-skin workings of the dog. It is the foundation for all gait and locomotion books which have been written since.

The Dog in Action

Human footprints provide some of the most emotive and tangible evidence of our ancestors. They provide evidence of stature, presence, behaviour and in the case of early hominin footprints, evidence with respect to the evolution of human gait and foot anatomy. While human footprint sites are rare in the geological record the number of sites around the World has increased in recent years, along with the analytical tools available for their study. The aim of this book is to provide a definitive review of these recent developments with specific reference to the increased availability of three-dimensional digital elevation models of human tracks at many key sites. The book is divided into eight chapters. Following an introduction the second chapter reviews modern field methods in human ichnology focusing on the development of new analytical tools. The third chapter then reviews the major footprint sites around the World including details on several unpublished examples. Chapters then follow on the role of geology in the formation and preservation of tracks, on the inferences that can be made from human tracks and the final chapter explores the application of this work to forensic science. Audience: This volume will be of interest to researchers and students across a wide range of disciplines – sedimentology, archaeology, forensics and palaeoanthropology.

Human Footprints: Fossilised Locomotion?

This book is about how animals travel around on land, in water and in the air. It is mainly about mechanisms of locomotion, their limitations and their energy requirements. There is some information about muscle physiology in Chapter 1, but only as much as seems necessary for the discussions of mechanisms and energetics. There is information in later chapters about the patterns of repetitive movement involved, for instance, in different gaits, but nothing about nervous mechanisms of coordination. I have tried to include most of the widely-used methods of locomotion, but have not thought it sensible to try to mention every variety of locomotion used by animals. This book is designed for undergraduates, but I hope that other people will also find it interesting. It is possible and sometimes illuminating to use complex mathematics in discussions of animal locomotion. This book includes many equations, but little mathematics. Such mathematics as there is, is simple. Discussions of the mechanisms and energetics of locomotion inevitably involve mechanics. I expect that some readers will know a lot of mechanics, and some hardly any. I have tried to help the latter without boring the former, by putting a summary of the necessary mechanics in an appendix (p. 140). References from the main text to the appendix will tell readers where they can find help, if they need it. Figures and equations in the appendix have numbers distinguished by a prefix A (for instance, Figure A.3).

Locomotion of Animals

Neuromechanics is a new, quickly growing field of neuroscience research that merges neurophysiology, biomechanics and motor control and aims at understanding living systems and their elements through interactions between their neural and mechanical dynamic properties. Although research in Neuromechanics is not limited by computational approaches, neuromechanical modeling is a powerful tool that allows for integration of massive knowledge gained in the past several decades in organization of motion related brain and spinal cord activity, various body sensors and reflex pathways, muscle mechanical and physiological properties and detailed quantitative morphology of musculoskeletal systems. Recent work in neuromechanical modeling has demonstrated advantages of such an integrative approach and led to discoveries of new emergent properties of neuromechanical systems. Neuromechanical Modeling of Posture and Locomotion will cover a wide range of topics from theoretical studies linking the organization of reflex pathways and central pattern generating circuits with morphology and mechanics of the musculoskeletal system (Burkholder; Nichols; Shevtsova et al.) to detailed neuromechanical models of postural and locomotor control (Bunderson; Edwards, Marking et al., Ting). Furthermore, uniquely diverse modeling approaches will be presented in the book including a theoretical dynamic analysis of locomotor phase transitions (Spardy and Rubin), a hybrid computational modeling that allows for in vivo interactions between parts of a living organism and a computer model (Edwards et al.), a physical neuromechanical model of the human locomotor system (Lewis), and others.

Neuromechanical Modeling of Posture and Locomotion

Design and Operation of Locomotion Systems examines recent advances in locomotion systems with multidisciplinary viewpoints, including mechanical design, biomechanics, control and computer science. In particular, the book addresses the specifications and requirements needed to achieve the proper design of locomotion systems. The book provides insights on the gait analysis of humans by considering image capture systems. It also studies human locomotion from a rehabilitation viewpoint and outlines the design and operation of exoskeletons, both for rehabilitation and human performance enhancement tasks. Additionally, the book content ranges from fundamental theory and mathematical formulations, to practical implementations and experimental testing procedures.

Design and Operation of Human Locomotion Systems

How many ways do we move around? Explore five different kinds of Creative Movement in Locomotion!

March, Hop, Skip, Gallop, Run.

Locomotion!

Jacqueline Woodson--New York Times Bestselling, National Book Award and Newbery Honor winning author--writes a rich story of a family adapting to change as they hold on to the past and embrace the future. With Coretta Scott King Award-winning illustrator James Ransome. During the time of the Great Migration, millions of African American families relocated from the South, seeking better opportunities. The story of one family's journey north during the Great Migration starts with a little girl in South Carolina who finds a rope under a tree one summer. She has no idea the rope will become part of her family's history. But for three generations, that rope is passed down, used for everything from jump rope games to tying suitcases onto a car for the big move north to New York City, and even for a family reunion where that first little girl is now a grandmother.

This Is the Rope

This book tells of Eadweard Muybridge's invention of very fast photography and his discovery of how animals and people run.

Muybridge and the Riddle of Locomotion

This book addresses instruments, methodologies and diagnostic methods used to evaluate and diagnose human movement, locomotion and physical status in general. Starting from historical perspective, the idea of understanding human locomotion by applying technical measurement devices and incorporating measurement data into physical representation of gross body movement is presented and explained, an approach known as inverse dynamics. With this approach as a kind of umbrella concept, components of measurement systems including relevant signal and data processing methods are described. Modern instruments to capture body movement by measuring its kinematics, kinetics and surface electromyography (sEMG) are thus described; all systems being used dominantly—if not exclusively—in a movement analysis laboratory setting. Focusing mainly on human posture and gait, but including also examples of movement patterns from selected kinesiological and sports activities, the book attempts to present essentials of biomechanics and biomedical engineering approach to this subject matter. It illustrates how data collected and elaborated by modern engineering technology can complement traditional expert knowledge of a kinesiologist or a medical doctor. The book is applicable in the fields of sports, physical activities, as well as in medical diagnostics and rehabilitation. The examples of this book's practical application might be in evaluation of efficiency of human gait, in evaluation of skeletal muscle fatigue in physical exercise, in biomechanical diagnostics of traumatological conditions requiring orthopaedic treatment and the like. This book can also be used in planning and executing research endeavours, particularly in a clinical context as a reference for various diagnostics procedures. It presents the lecture notes of a course carrying the same name within Medical Studies in English at the University of Zagreb for more than a decade.

Measurement and Analysis of Human Locomotion

This book examines how animals move, comparing running, swimming, and flying. It also reviews the common principles of design and movement that animals have evolved to move through very different physical environments.

Neural Control of Locomotion

Animal Locomotion: Physical Principles and Adaptations is a professional-level, state of the art review and reference summarizing the current understanding of macroscopic metazoan animal movement. The

comparative biophysics, biomechanics and bioengineering of swimming, flying and terrestrial locomotion are placed in contemporary frameworks of biodiversity, evolutionary process, and modern research methods, including mathematical analysis. The intended primary audience is advanced-level students and researchers primarily interested in and trained in mathematics, physical sciences and engineering. Although not encyclopedic in its coverage, anyone interested in organismal biology, functional morphology, organ systems and ecological physiology, physiological ecology, molecular biology, molecular genetics and systems biology should find this book useful.

Animal Locomotion

Nowadays, multiple attention have been paid on a robot working in the human living environment, such as in the field of medical, welfare, entertainment and so on. Various types of researches are being conducted actively in a variety of fields such as artificial intelligence, cognitive engineering, sensor- technology, interfaces and motion control. In the future, it is expected to realize super high functional human-like robot by integrating technologies in various fields including these types of researches. The book represents new developments and advances in the field of bio-inspired robotics research introducing the state of the art, the idea of multi-locomotion robotic system to implement the diversity of animal motion. It covers theoretical and computational aspects of Passive Dynamic Autonomous Control (PDAC), robot motion control, multi legged walking and climbing as well as brachiation focusing concrete robot systems, components and applications. In addition, gorilla type robot systems are described as hardware of Multi-Locomotion Robotic system. It is useful for students and researchers in the field of robotics in general, bio-inspired robots, multi-modal locomotion, legged walking, motion control, and humanoid robots. Furthermore, it is also of interest for lecturers and engineers in practice building systems cooperating with humans.

Animal Locomotion

The study of primate locomotion is a unique discipline that by its nature is interdisciplinary, drawing on and integrating research from ethology, ecology, comparative anatomy, physiology, biomechanics, paleontology, etc. When combined and focused on particular problems this diversity of approaches permits unparalleled insight into critical aspects of our evolutionary past and into a major component of the behavioral repertoire of all animals. Unfortunately, because of the structure of academia, integration of these different approaches is a rare phenomenon. For instance, papers on primate behavior tend to be published in separate specialist journals and read by subgroups of anthropologists and zoologists, thus precluding critical syntheses. In the spring of 1995 we overcame this compartmentalization by organizing a conference that brought together experts with many different perspectives on primate locomotion to address the current state of the field and to consider where we go from here. The conference, Primate Locomotion-1995, took place thirty years after the pioneering conference on the same topic that was convened by the late Warren G. Kinzey at Davis in 1965.

Multi-Locomotion Robotic Systems

Fish accomplish most of their basic behaviors by swimming. Swimming is fundamental in a vast majority of fish species for avoiding predation, feeding, finding food, mating, migrating and finding optimal physical environments. Fish exhibit a wide variety of swimming patterns and behaviors. This treatise looks at fish swimming from the behavioral and

Neurobiology of Vertebrate Locomotion

Bioinspired Legged Locomotion: Models, Concepts, Control and Applications explores the universe of legged robots, bringing in perspectives from engineering, biology, motion science, and medicine to provide a comprehensive overview of the field. With comprehensive coverage, each chapter brings outlines, and an abstract, introduction, new developments, and a summary. Beginning with bio-inspired locomotion concepts,

the book's editors present a thorough review of current literature that is followed by a more detailed view of bouncing, swinging, and balancing, the three fundamental sub functions of locomotion. This part is closed with a presentation of conceptual models for locomotion. Next, the book explores bio-inspired body design, discussing the concepts of motion control, stability, efficiency, and robustness. The morphology of legged robots follows this discussion, including biped and quadruped designs. Finally, a section on high-level control and applications discusses neuromuscular models, closing the book with examples of applications and discussions of performance, efficiency, and robustness. At the end, the editors share their perspective on the future directions of each area, presenting state-of-the-art knowledge on the subject using a structured and consistent approach that will help researchers in both academia and industry formulate a better understanding of bioinspired legged robotic locomotion and quickly apply the concepts in research or products. - Presents state-of-the-art control approaches with biological relevance - Provides a thorough understanding of the principles of organization of biological locomotion - Teaches the organization of complex systems based on low-dimensional motion concepts/control - Acts as a guideline reference for future robots/assistive devices with legged architecture - Includes a selective bibliography on the most relevant published articles

Research Report - U. S. Land Locomotion Research Laboratory, Center Line, Michigan

The first edition of Equine Locomotion has established itself as the book in the equine literature that discusses all aspects of equine locomotion and gait analysis, written by an international team of editors and contributors. The new edition continues this trend and gives the reader a complete picture of the horse in motion, at the same time including many recent findings in this area. The book begins with a history of man's association with the horse and then continues to discuss with comprehensive descriptions of the present state of knowledge beginning with the initiation of gait and ending with the more scientific area of computer modeling. In the new edition, the list of contributors continues to comprise of authors who are acknowledged experts in their subject areas and includes many new illustrations. •international team of editors and contributors, with leading experts from the USA, the Netherlands, Sweden and France (all centres of excellence for the study of equine locomotion) •editors are from two of the worlds leading locomotion centres – Utrecht and Michigan •highly illustrated with nearly 500 detailed line drawings and illustrations •covers all you will ever need to know about equine locomotion, gait analysis and much more •international team of editors and contributors, with leading experts from the USA, the Netherlands, Sweden and France (all centres of excellence for the study of equine locomotion) •editors are from two of the worlds leading locomotion centres – Utrecht and Michigan •highly illustrated with nearly 500 detailed line drawings and illustrations •covers all you will ever need to know about equine locomotion, gait analysis and much more

Primate Locomotion

This volume publishes the review articles presented by the invited speakers at the Satellite Meeting to the Barany Society Meeting held in Bologna, Italy during June 1987. The subject matter in this book is divided into seven main sections. The first three present basic neuroanatomical and neurophysiological aspects of vestibulospinal reflexes and document the neck afferent and visual influences on these reflexes. The following sections deal with the control of locomotion, posture, and eye-head-trunk coordination by vestibulospinal signals. The final section provides current knowledge on the processes underlying compensation of vestibulospinal deficits. An overall review precedes each main section so that the reader is informed as to which questions are still controversial and require further investigation. In this way a basis is provided for those needing a current account of the field of vestibulospinal reflexes. Due to the extensive length of the contents, only the number of articles presented per session is listed below.

Fish Locomotion

This book presents a bio-inspired hierarchical control scheme step by step toward developing limbless robots capable of 3D locomotion, fast reflex response, as well as sophisticated reaction to environmental stimuli. This interdisciplinary book introduces how to combine biological concept with locomotion control of

limbless robots. The special features of the book include limbless locomotion classification and control, design of biological locomotor and the integration of sensory information into the locomotor using artificial intelligence methods, and on-site demonstrations of limbless locomotion in different scenarios. The book is suitable for readers with engineering background, especially for researchers focused on bio-inspired robots.

Bioinspired Legged Locomotion

The Novartis Foundation Series is a popular collection of the proceedings from Novartis Foundation Symposia, in which groups of leading scientists from a range of topics across biology, chemistry and medicine assembled to present papers and discuss results. The Novartis Foundation, originally known as the Ciba Foundation, is well known to scientists and clinicians around the world.

Equine Locomotion

The Neural Control of Locomotion: Current Knowledge and Future Research

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